March 2nd, Sat.	HALL	Room-A	Room-B	Room-C	Foyer
AM 9:30-9:40	Opening				
AM 9:40-10:40	Plenaly 1 Prof. Ercan Altinsoy, Ph.D. Recent Advances and Next Generation Sensor and Actuator Materials and Solutions for Haptic Interfaces - Perception based				
AM 11:00-12:40		IS2 (4) Data-driven based Novel/Advanced Control for Nonlinear Mechanical Systems	3	TT2(5) Actuation and Automotive Systems memo: TT2(1)+TT4(2)+TT3(2) (5)	
PM1 13:50-14:20		P1A <poster-shotgun></poster-shotgun>	P1B <poster-shotgun></poster-shotgun>	P1C <poster-shotgun></poster-shotgun>	
PM2 14:40-16:40		IS1 (6) Precision Control Methodologies for Next Generation Mechatronic Systems	SS4 (6) Advanced motion control methods for modern mechatronics systems		Poster Session P1A P1B P1C

March 3rd, Sun.	HALL	Room-A	Room-B	Room-C	Foyer
AM 9:40-10:40	Plenaly 2 Prof. Ya-Jun Pan, Ph.D. Effective Cooperation with Intelligent Adaptive Robots				
AM 11:00-12:40		Industrial Applications		TT5-1 (5) Robotics and Mechatronics [1]	
PM1 13:50-14:20		P2A <poster-shotgun></poster-shotgun>	P2B <poster-shotgun></poster-shotgun>	P2C <poster-shotgun></poster-shotgun>	
PM2 14:40-16:40	JIA-to-SAMCON				Poster Session P2A P2B P2C

March 4th, Mon.	HALL	Room-A	Room-B	Room-C	Foyer
AM 9:40-10:40	Plenaly 3 Prof. Tetsuya Ogata, Dr. Eng. Dynamic adaptability in Al with active Inference for real-world robots				
AM 11:00-12:40			SS1 (4) Motion Control for Aeronautics and Astronautics Application	TT5-2 (5) Robotics and Mechatronics [2]	
PM1 13:50-14:20		P3A <poster-shotgun></poster-shotgun>	P4B <poster-shotgun></poster-shotgun>	P5C <poster-shotgun></poster-shotgun>	
PM2 14:40-16:40		TT3 (6) Control Theory and Its Applications	TT1 (6) Sensing and Its Applications		Poster Session P3A P3B P3C